

The “NE” Integral Transform and fractional differential equations

Ervenila Musta (Xhaferraj)

Department of Mathematical Engineering , Faculty of
 Mathematical Engineering and Physics Engineering,
 Polytechnic University of Tirana.
 Tirane, Albania
 ervimst@yahoo.com

Anita Caushi

Department of Mathematical Engineering , Faculty of
 Mathematical Engineering and Physics Engineering,
 Polytechnic University of Tirana.
 Tirane, Albania
 anita_caushi@yahoo.com

Abstract—This article demonstrates how the new Double “NE” integral transform is successfully implemented o obtain the exact solutions of fractional nonlinear partial differential equations by considering specified conditions. Several properties and theorems related to existing conditions, partial derivatives, the double convolution theorem, and others are presented.

Keywords—“NE” integral transform; fractional differential equation; double “NE” integral transform;

I.

INTRODUCTION

Fractional partial differential equations appear in various applications of science, such as chemistry, physics, engineering and mathematics, which is why researchers have established many techniques for solving such equations such as the homotopy perturbation method, variation iteration method, Adomian decomposition method, finite difference method and others. The method of double integral transforms is a hot topic in recent research, and it depends on applying a single transformation twice on functions of two variables or applying two different transformations on the same function. This new approach is a powerful tool for solving PDEs. Although double integral transformations, their properties and theorems are recent studies, they have attracted the interest of many mathematicians. In this section, we present the definition of “NE” of functions of two variables and the existence conditions and some basic properties of the new double transform are introduced.

A. Basic Definitions and Theorems of” NE” Integral Transform

In this section, we present the definition of “NE” of functions of two variables, and the existence conditions and some basic properties of the new double transform are introduced .

Definition 3. The “NE” integral transform of the continuous function $f(x, t)$ of two variables $x > 0$ and $t > 0$ is given by

$$N_2\{f(x, t)\} = E(s; u, v) = \frac{1}{su} \frac{1}{sv} \iint_0^\infty e^{-\left(\frac{s}{u}x + \frac{s}{v}t\right)} f(x, t) dx dt$$

provided the integral exists

The “NE” is linear, since

$$N_2[\{af(x, t) + bg(x, t)\}] = aN_2\{f(x, t)\} + bN_2\{g(x, t)\}$$

where a and b are constants.

The inverse “NE” integral transform is given by

$$N_2^{-1}[E(s; u, v)] = f(x, t) \\ = \frac{1}{2\pi i} \int_{c-i\infty}^{c+i\infty} e^{\frac{sx}{u}} s ds \frac{1}{2\pi i} \int_{\omega-i\infty}^{\omega+i\infty} e^{\frac{st}{v}} uv E(s; u, v) du$$

In this article, we implement the “NE” integral transform to solve families of FPDEs of $AD_x^\alpha f(x, t) + BD_t^\beta f(x, t) + CLf(x, t) = z(x, t)$ (1) $(x, t) > 0, n - 1 < \alpha \leq n, m - 1 < \beta \leq m$ and $m, n \in N$,

With the initial condition $\frac{\partial^i f(x, 0)}{\partial t^i} = g_i(x)$, $i = 0, 1, \dots, m - 1$ (2)

and the boundary conditions

$$\frac{\partial^j f(0, t)}{\partial t^j} = h_j(x) , j = 0, 1, \dots, n - 1$$
 (3)

where A, B, and C are real constants, D_x^α and D_t^β are the fractional Caputo’s derivatives with respect to x and t, respectively, L is a linear operator and z(x, t) is the source function. The main motivation of the present study is to expand the applications of “NE” integral transform by using it to solve FPDEs. We show the efficiency of the proposed method by applying the “NE” integral transform to several interesting applications to obtain the exact solutions and analyze the results. The novelty of this work arises from the establishment of a new simple formula for solving PDEs of fractional orders. The simplicity and applicability of this new formula is illustrated by handling some applications, where we use the new approach to solve some important FPDEs. This article is organized as follows: in the next two sections, we

present some basic definitions and theorems related to our work.

A new algorithm for solving families of FPDEs using "NE" integral transform is presented. Several examples are given to demonstrate the proposed technique.

Definition : A function $f(x,t)$ defined on $[0,X] \times [0,T]$ is called function of exponential orders α and β as $x \rightarrow \infty$ and $t \rightarrow \infty$, if $\exists M > 0$ such that $\forall x > X$ and $\forall t > T$, we have
 $|f(x,t)| \leq Me^{\alpha x + \beta t}$

Theorem 3 : (Existence condition). Let $f(x,t)$ be a continuous function on the region $[0,X] \times [0,T]$. If $f(x,t)$ is exponential orders λ and γ , then "NE" integral transform of $f(x,t)$ exists, for $Re[s] > 0$, $Re\left[\frac{s}{u}\right] > \alpha$ and $Re\left[\frac{s}{v}\right] > \beta$.

Proof : The "NE" integral transform definition yields that

$$|E(s; u, v)| = \left| \frac{1}{su} \frac{1}{sv} \int_0^\infty \int_0^\infty e^{-\left(\frac{s}{u}x + \frac{s}{v}t\right)} f(x, t) dx dt \right|$$

$$\leq \frac{1}{su} \frac{1}{sv} \int_0^\infty \int_0^\infty e^{-\left(\frac{s}{u}x + \frac{s}{v}t\right)} |f(x, t)| dx dt$$

$$\leq \frac{M}{suv} \int_0^\infty e^{-\left(\frac{s}{u}-\alpha\right)x} dx \int_0^\infty e^{-\left(\frac{s}{v}-\beta\right)t} dt$$

$$\frac{M}{suv\left(\frac{s}{u}-\alpha\right)\left(\frac{s}{v}-\beta\right)} = \frac{M}{s(s-au)(s-bv)}$$

$$Re[s] > 0, Re\left[\frac{s}{u}\right] > \alpha \text{ and } Re\left[\frac{s}{v}\right] > \beta.$$

The proof is completed.

Theorem : (Derivate Propertie) .If $E(s; u, v) = N_2\{f(x, t)\}$, then

1. $N_2\left\{\frac{\partial f(x,t)}{\partial t}\right\} = -p_2(s, v)N\{f(x, 0)\} + q_2(s, v)N_2\{f(x, t)\} = -\frac{1}{sv}N\{f(x, 0)\} + \frac{s}{v}N_2\{f(x, t)\}$
2. $N_2\left\{\frac{\partial f(x,t)}{\partial x}\right\} = -p_1(s, u)N\{f(0, t)\} + q_1(s, u)N_2\{f(x, t)\} = -\frac{1}{su}N\{f(0, t)\} + \frac{s}{u}N_2\{f(x, t)\}$
3. $N_2\left\{\frac{\partial^2 f(x,t)}{\partial x^2}\right\} = -p_1(s, u)[N\{f_x(0, t)\} + q_1(s, u)N\{f(0, t)\}] + q_1(s, u)^2 N_2\{f(x, t)\} = -\frac{1}{su}[N\{f_x(0, t)\} + \frac{s}{u}N\{f(0, t)\}] + \frac{s^2}{u^2}N_2\{f(x, t)\}$

$$4. N_2\left\{\frac{\partial^2 f(x,t)}{\partial t^2}\right\} = -p_2(s, v)[N\{f_t(x, 0)\} + q_2(s, v)N\{f(x, 0)\}] + q_2(s, v)^2 N_2\{f(x, t)\} = -\frac{1}{sv}[N\{f_x(x, 0)\} + \frac{s}{v}N\{f(x, 0)\}] + \frac{s^2}{v^2}N_2\{f(x, t)\}$$

Theoreme : (Convolution theorem)

Let $N_2[f(x, t)]$ and $N_2[g(x, t)]$ are exists then

$$N_2[(f ** g)] = uv s F(s, u, v) G(s, u, v)$$

Where $f ** g$ is convolution of two function f and g defined by

$$[(f ** g)] = \int_0^x \int_0^t f(x - \rho, t - \tau) g(\rho, \tau) d\rho d\tau$$

$$N_2[(f ** g)] = \frac{1}{su} \frac{1}{sv} \int_0^\infty \int_0^\infty e^{-\left(\frac{s}{u}x + \frac{s}{v}t\right)} (f ** g)(x, t) dx dt$$

$$= \frac{1}{su} \frac{1}{sv} \int_0^\infty \int_0^\infty e^{-\left(\frac{s}{u}x + \frac{s}{v}t\right)} \left[\int_0^x \int_0^t f(x - \rho, t - \tau) g(\rho, \tau) d\rho d\tau \right] dx dt$$

Using the Heaviside unit step function, the above equation can be written as

$$N_2[(f ** g)] = \frac{1}{su} \frac{1}{sv} \int_0^\infty \int_0^\infty e^{-\left(\frac{s}{u}x + \frac{s}{v}t\right)} \left[\int_0^\infty \int_0^\infty f(x - \rho, t - \tau) H(x - \rho, t - \tau) g(\rho, \tau) d\rho d\tau \right] dx dt$$

$$N_2[(f ** g)] = \int_0^\infty \int_0^\infty g(\rho, \tau) d\rho d\tau \left[\frac{1}{su} \frac{1}{sv} \int_0^\infty \int_0^\infty e^{-\left(\frac{s}{u}x + \frac{s}{v}t\right)} f(x - \rho, t - \tau) H(x - \rho, t - \tau) dx dt \right]$$

$$N_2[(f ** g)] = \int_0^\infty \int_0^\infty g(\rho, \tau) d\rho d\tau \left(e^{-\frac{s}{u}\rho - \frac{s}{v}\tau} N_2[f(x, t)] \right)$$

$$= N_2[f(x, t)] \int_0^\infty \int_0^\infty e^{-\frac{s}{u}\rho - \frac{s}{v}\tau} g(\rho, \tau) d\rho d\tau$$

$$= uv s N_2[f(x, t)] N_2[g(x, t)]$$

B. Algorithm of double "NE" integral transform

In this section, we present the technique of using double "NE" integral transform to solve families of FPDEs. In order to achieve our goal, we have to calculate double "NE" integral transform for the nonlocal Caputo fractional

derivative in the following lemma.

Double “NE” integral transform of Fractional Derivatives

Lemma 1 : The double “NE” integral transform for Caputo fractional derivatives can expressed as

$$\begin{aligned}
 1. \quad N_2[D_x^\alpha f(x, t)] &= \left(\frac{s}{u}\right)^\alpha N_2\{f(x, t)\} - \sum_{i=0}^{n-1} \frac{s^{\alpha-i-2}}{u^{\alpha-i}} \frac{\partial^i f(0, t)}{\partial x^i} = \left(\frac{s}{u}\right)^\alpha E(s; u, v) - \sum_{i=0}^{n-1} \frac{s^{\alpha-i-2}}{u^{\alpha-i}} \frac{\partial^i f(0, t)}{\partial x^i}, \\
 2. \quad N_2[D_t^\alpha f(x, t)] &= \left(\frac{s}{v}\right)^\alpha N_2\{f(x, t)\} - \sum_{i=0}^{n-1} \frac{s^{\alpha-i-2}}{v^{\alpha-i}} \frac{\partial^i f(x, 0)}{\partial t^i} = \left(\frac{s}{v}\right)^\alpha E(s; u, v) - \sum_{i=0}^{n-1} \frac{s^{\alpha-i-2}}{v^{\alpha-i}} \frac{\partial^i f(x, 0)}{\partial t^i}
 \end{aligned}$$

$$n - 1 < \alpha \leq n$$

Proof of Lemma : 1. Applying double “NE” integral transform on $D_x^\alpha f(x, t)$, we obtain :

$$N_2[D_x^\alpha f(x, t)] = N_2 \left[\frac{1}{\Gamma(n-\alpha)} \int_0^x (x-\beta)^{n-\alpha-1} \frac{\partial^n f(\beta-t)}{\partial \beta^n} d\beta \right]$$

From the definition of the convolution, we have

$$\begin{aligned}
 N_2[D_x^\alpha f(x, t)] &= N_2 \left[\frac{1}{\Gamma(n-\alpha)} (x^{n-\alpha-1} * \frac{\partial^n f(x, t)}{\partial x^n}) \right] = N_t \left[\frac{1}{\Gamma(n-\alpha)} N_x(x^{n-\alpha-1} * \frac{\partial^n f(x, t)}{\partial x^n}) \right]
 \end{aligned}$$

Using the convolution property of “NE” transform, we obtain

$$\begin{aligned}
 N_2[D_x^\alpha f(x, t)] &= N_t \left[\frac{1}{\Gamma(n-\alpha)} (u s N_x[x^{n-\alpha-1}] N_x \left[\frac{\partial^n f(x, t)}{\partial x^n} \right]) \right]
 \end{aligned}$$

Applying the derivative property of “NE” transform we obtain

$$\begin{aligned}
 N_2[D_x^\alpha f(x, t)] &= \frac{1}{\Gamma(n-\alpha)} N_t \left[u s \frac{u^{n-\alpha-1}}{s^{n-\alpha+1}} \Gamma(n-\alpha) \left(\left(\frac{s}{u}\right)^\alpha N_x\{f(x, t)\} - \left(\frac{s}{u}\right)^{n-2} f(0, t) - \dots - \frac{1}{su} \frac{\partial^{n-1} f(0, t)}{\partial x^{n-1}} \right) \right] \\
 &= \frac{1}{\Gamma(n-\alpha)} N_t \left[\frac{u^{n-\alpha}}{s^{n-\alpha}} \Gamma(n-\alpha) \left(\left(\frac{s}{u}\right)^\alpha N_x\{f(x, t)\} - \left(\frac{s}{u}\right)^{n-2} f(0, t) - \dots - \frac{1}{su} \frac{\partial^{n-1} f(0, t)}{\partial x^{n-1}} \right) \right] \\
 &= N_t \left[\frac{s^\alpha}{u^\alpha} N_x\{f(x, t)\} - \frac{s^{\alpha-2}}{u^\alpha} f(0, t) - \dots - \frac{u^{n-\alpha-1}}{s^{n-\alpha+1}} \frac{\partial^{n-1} f(0, t)}{\partial x^{n-1}} \right] \\
 &= \left(\frac{s}{u}\right)^\alpha E(s; u, v) - \sum_{i=0}^{n-1} \frac{s^{\alpha-i-2}}{u^{\alpha-i}} \frac{\partial^i f(0, t)}{\partial x^i}
 \end{aligned}$$

2. In the same manner can proof the other equal .

Illustrative Examples

$$\begin{aligned}
 N_2[AD_x^\alpha f(x, t)] + N_2[BD_t^\beta f(x, t)] + N_2[CLf(x, t)] &= N_2[Z(x, t)]
 \end{aligned}$$

which implies

$$\begin{aligned}
 A \left(\left(\frac{s}{u}\right)^\alpha E(s; u, v) - \sum_{j=0}^{n-1} \frac{s^{\alpha-i-2}}{u^{\alpha-i}} \frac{\partial^i f(0, t)}{\partial x^i} \right) &+ B \left(\left(\frac{s}{v}\right)^\beta E(s; u, v) - \sum_{i=0}^{m-1} \frac{s^{\beta-j-2}}{v^{\beta-j}} \frac{\partial^j f(x, 0)}{\partial t^j} \right) \\
 + CN_2[Lf(x, t)] &= Z(s; u, v)
 \end{aligned}$$

Furthermore, we apply the single “NE” transform to the ICs (3), and to the BCs (2), to obtain

$$N_x \left[\frac{\partial^j f(x, 0)}{\partial t^j} \right] = N[g_j(x)] = G_j(s), \quad j = 0, 1, \dots, m-1 \quad (5)$$

$$N_t \left[\frac{\partial^i f(0, t)}{\partial t^i} \right] = N[h_i(x)] = H_i(s), \quad i = 0, 1, \dots, n-1 \quad (6)$$

Simplifying Equation (4), and substituting the values in Equations (5) and (6), we have

$$\begin{aligned}
 E(s; u, v) &= \frac{1}{A \left(\frac{s}{u}\right)^\alpha + B \left(\frac{s}{v}\right)^\beta} \left(A \sum_{i=0}^{n-1} \frac{s^{\alpha-i-2}}{u^{\alpha-i}} H_i(s) + B \sum_{i=0}^{m-1} \frac{s^{\beta-i-2}}{v^{\beta-i}} G_j(s) \right) - CN_2[L(f(x, t))] + Z(s; u, v) \quad (7)
 \end{aligned}$$

Running the inverse “NE” integral transform, on both sides of Equation (7), we obtain

$$\begin{aligned}
 f(x, t) &= N_2^{-1} \left[\frac{1}{A \left(\frac{s}{u}\right)^\alpha + B \left(\frac{s}{v}\right)^\beta} \left(A \sum_{i=0}^{n-1} \frac{s^{\alpha-i-2}}{u^{\alpha-i}} H_i(s) + B \sum_{i=0}^{m-1} \frac{s^{\beta-i-2}}{v^{\beta-i}} G_j(s) \right) - CN_2[L(f(x, t))] + Z(s; u, v) \right]
 \end{aligned}$$

which is the solution of the target problem.

C . Conclusions

In this research, “NE” integral transform is applied to the Caputo fractional derivative to obtain a new interesting formula, that is implemented to solve families of FPDEs. We have presented a new method to obtain exact solutions of these equations. We show the reliability and efficiency of the proposed method

by presenting some interesting physical applications. In the future, we will pair “NE” integral transform with some iteration methods to solve nonlinear FPDEs, such as nonlinear telegraph equation, nonlinear wave equation, nonlinear Klein–Gordon and nonlinear Fokker–Planck.

REFERENCES

- [1] .Caputo, M.; Fabrizio, M. A new Definition of Fractional Derivative without Singular Kernel. *Prog. Fract. Differ. Appl.* 2015, 1, 73–85. 3. Algaht
- [2]. Algahtani, O.J.J. Comparing the Atangana–Baleanu and Caputo–Fabrizio derivative with fractional order: Allen Cahn model. *Chaos Solitons Fractals. Nonlinear Dyn. Complex.* 2016, 89, 552–559. [CrossRef]
- [3]. Atangana, A.; Baleanu, D. New fractional derivatives with nonlocal and non-singular kernel: Theory and application to heat transfer model. *Therm. Sci.* 2016, 20, 763–769. [CrossRef]
- [4]. Khalil, R.; Al Horani, M.; Yousef, A.; Sababheh, M. A new definition of fractional derivative. *J. Comput. Appl. Math.* 2014, 264, 65–70. [CrossRef]
- [5]. Dhunde, R.R.; Waghmare, G.L. Double Laplace transform combined with iterative method for solving non-linear telegraph equation. *J. Indian Math. Soc.* 2016, 83, 221–230. [Google Scholar]
- [6]. Elzaki, T.; Ahmed, S.; Areshi, M.; Chamekh, M. Fractional partial differential equations and novel double integral transform. *J. King Saud Univ. Sci.* 2022, 34, 101832. [Google Scholar] [CrossRef]
- [7]. Baleanu, D.; Hassan Abadi, M.; Jajarmi, A.; Zarghami Vahid, K.; Nieto, J.J. A new comparative study on the general fractional model of COVID-19 with isolation and quarantine effects. *Alex. Eng. J.* 2022, 61, 4779–4791. [Google Scholar] [CrossRef]
- [8]. Mishra, H.K.; Nagar, A.K. He-Laplace method for linear and nonlinear partial differential equations. *J. Appl. Math.* 2012, 2012, 180315. [Google Scholar]